

# Structural Iterative Rounding for Generalized $k$ -Median Problems

Anupam Gupta, Ben Moseley, **Rudy Zhou**

Carnegie Mellon

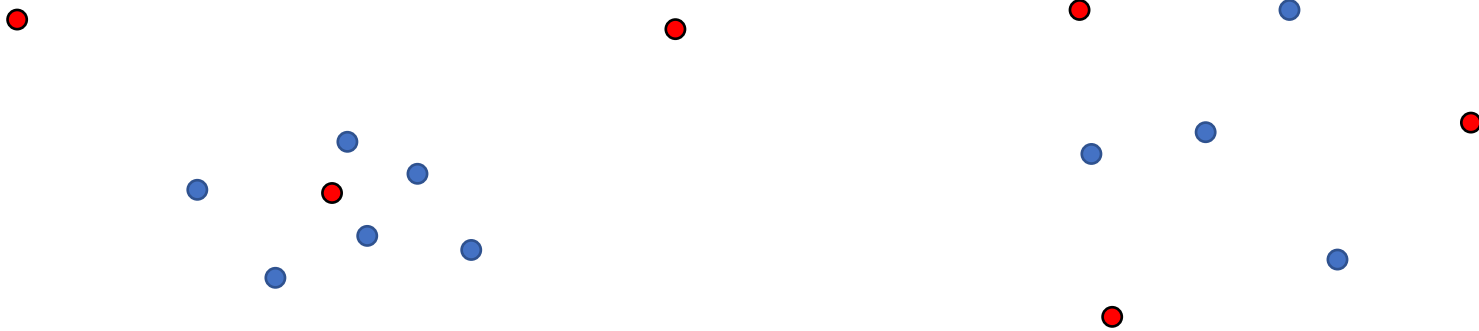
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  - $\mathcal{C}$  = set of Clients



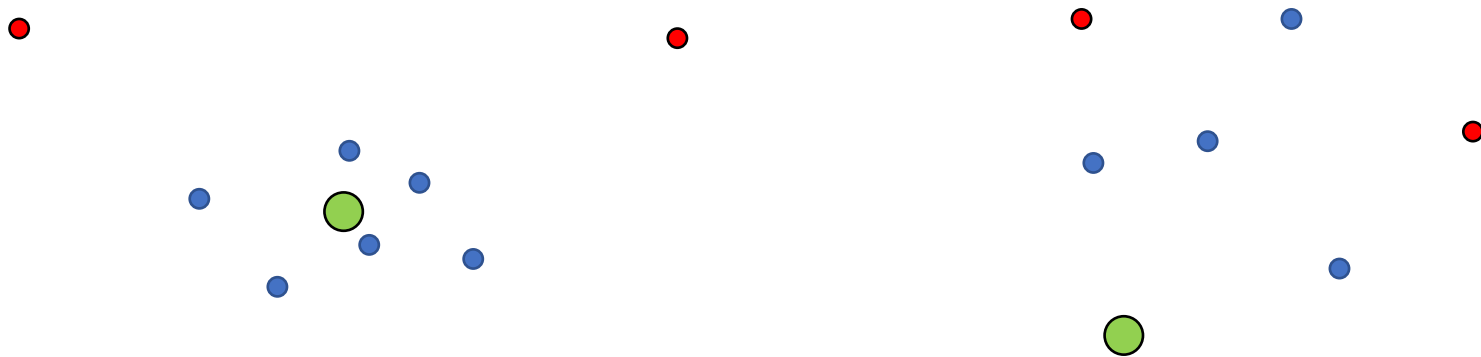
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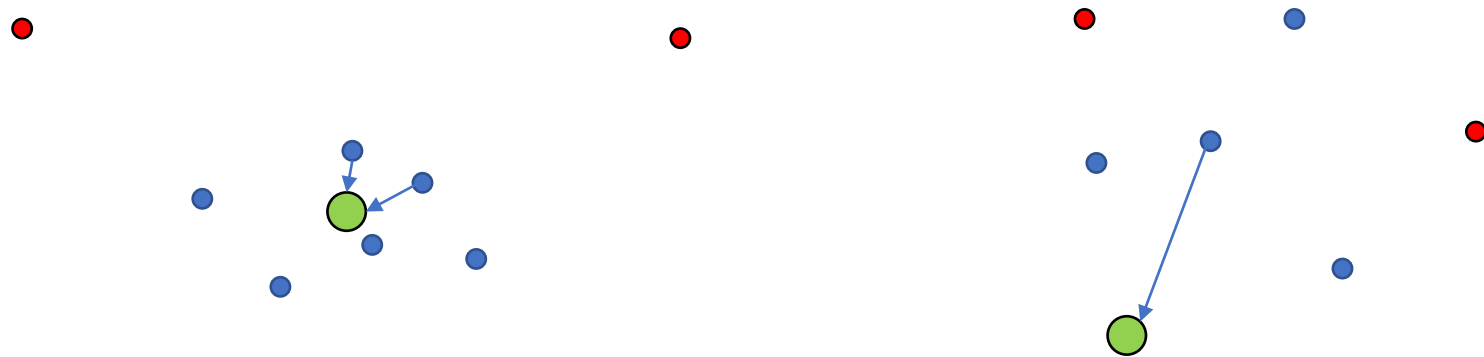


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## Objective:

minimize:  $\sum_{j \in C} \text{dist}(j, \text{nearest open facil.})$



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Best approx. for both is  $\sim 7$  via Iterative Rounding  
(KLS, 2018)


*Ravishankar Krishnaswamy, Shi Li, Sai Sandeep:*

*Constant approximation for  $k$ -median and  $k$ -means with outliers via iterative rounding. STOC 2018: 646-659*

# Improving on KLS: Our Results

- **Knapsack Median:**  $\sim 6.3$
- **$k$ -Median with Outliers:**  $\sim 6.9$
- **$k$  –Median with  $O(1)$  Side Constraints:**  $\sim 6.3$  (pseudo-approx.)

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# Basic LP: $k$ -Median with Outliers

$$\min \sum_{i \in F, j \in C} d(i, j) x_{ij}$$

$$x_{ij} \leq y_i \quad \forall i \in F, j \in C$$

$$\sum_{i \in F} x_{ij} \leq 1 \quad \forall j \in C$$

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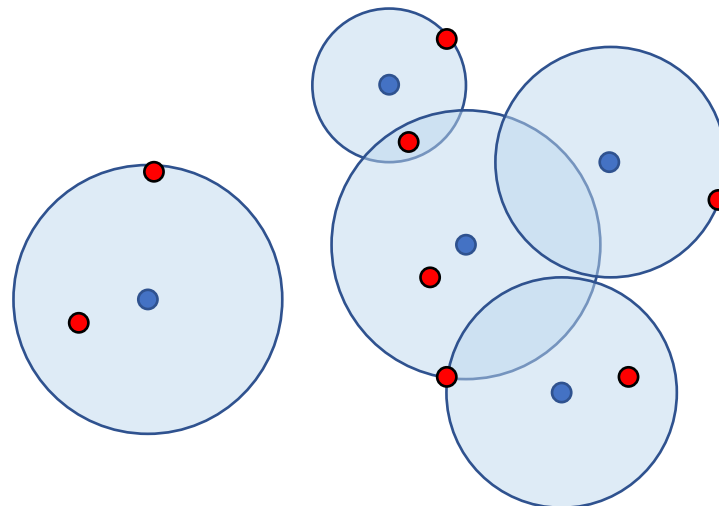
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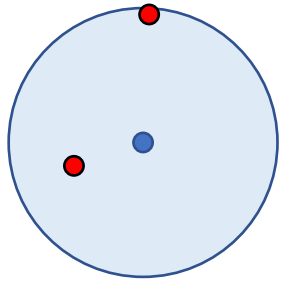
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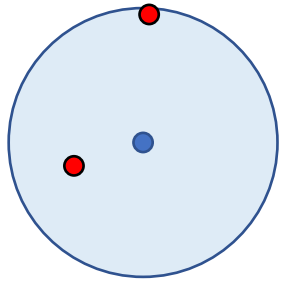


# 'Set Cover' LP: $k$ -Median with Outliers



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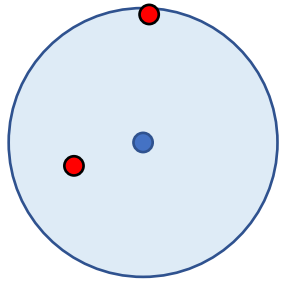


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$\text{Ball}_j = \text{Client } j\text{'s allowed connections}$



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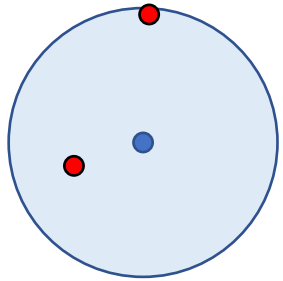
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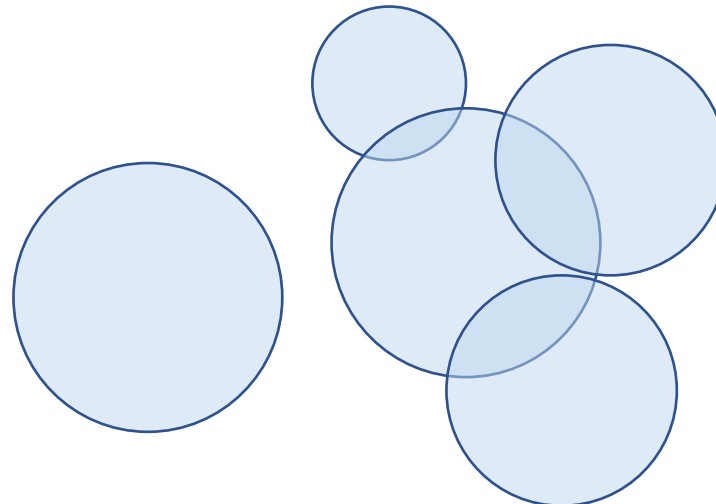
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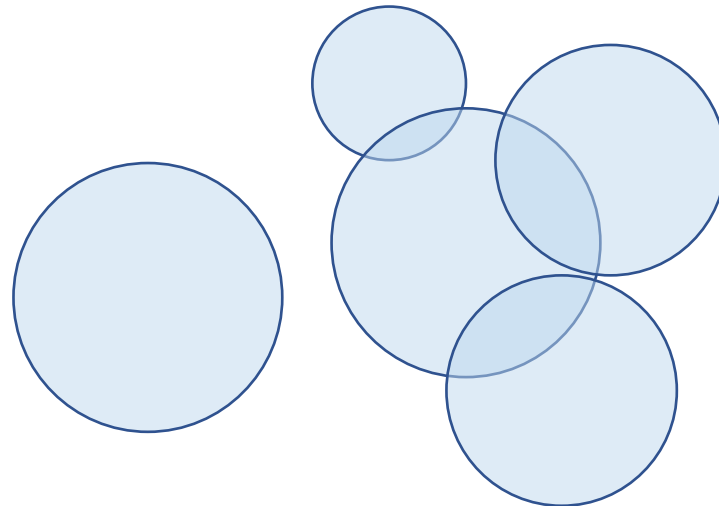
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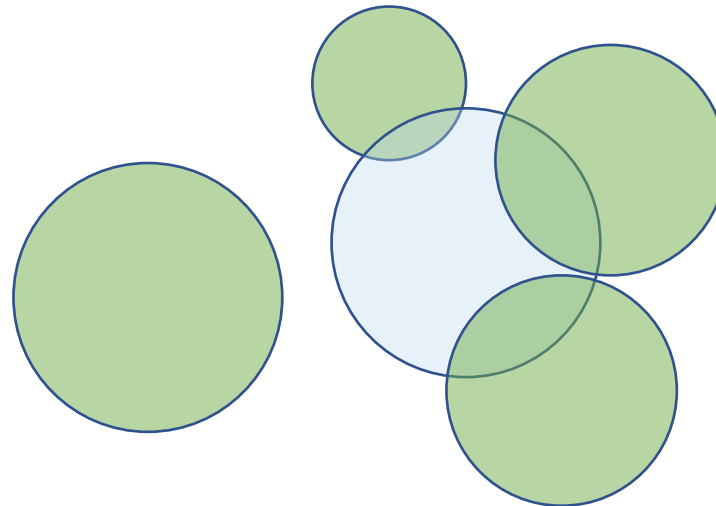
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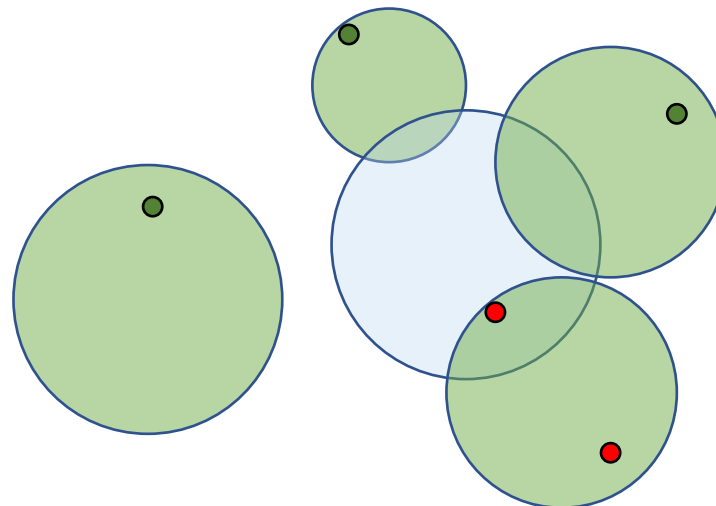
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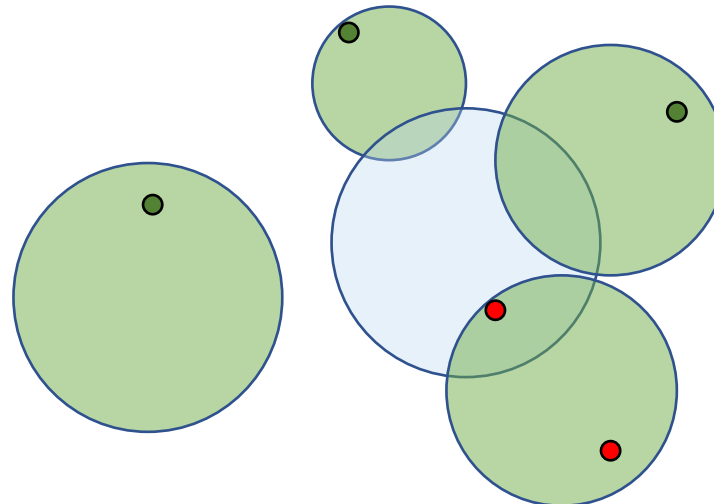
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**Main Idea:** Control tight balls



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- KLS:
  - Desired Structure = disjoint balls
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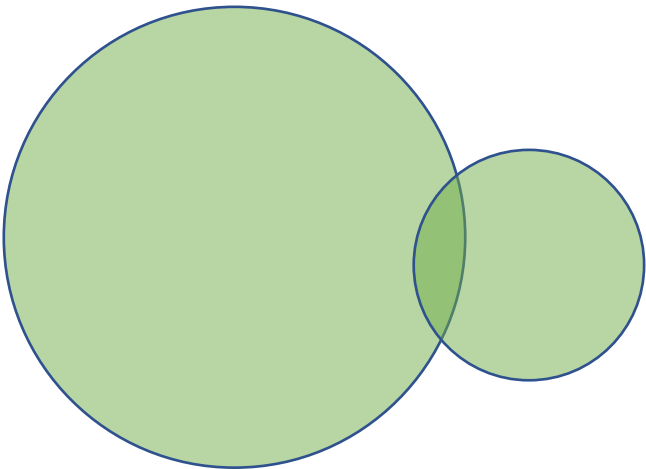
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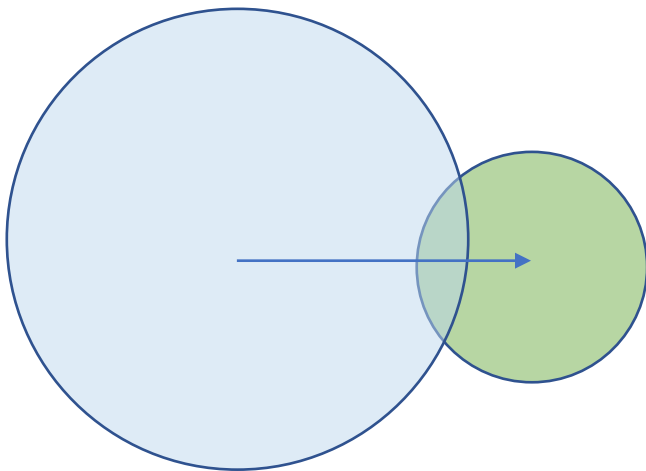
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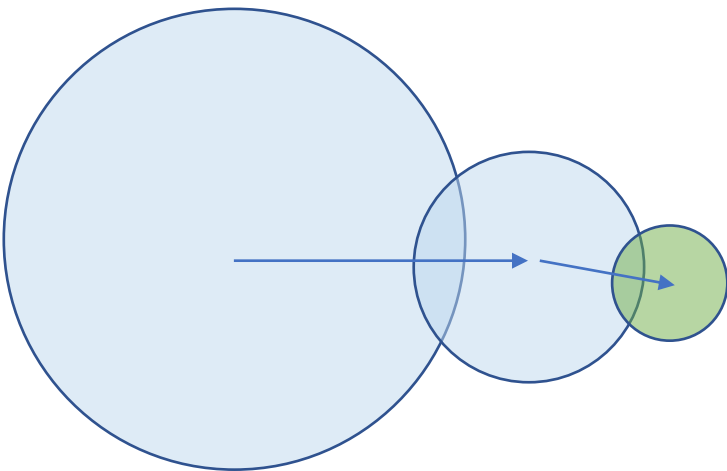
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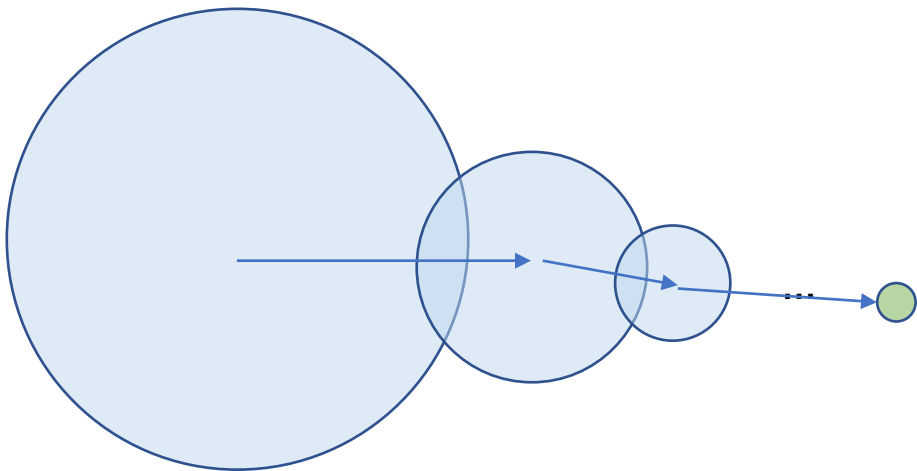
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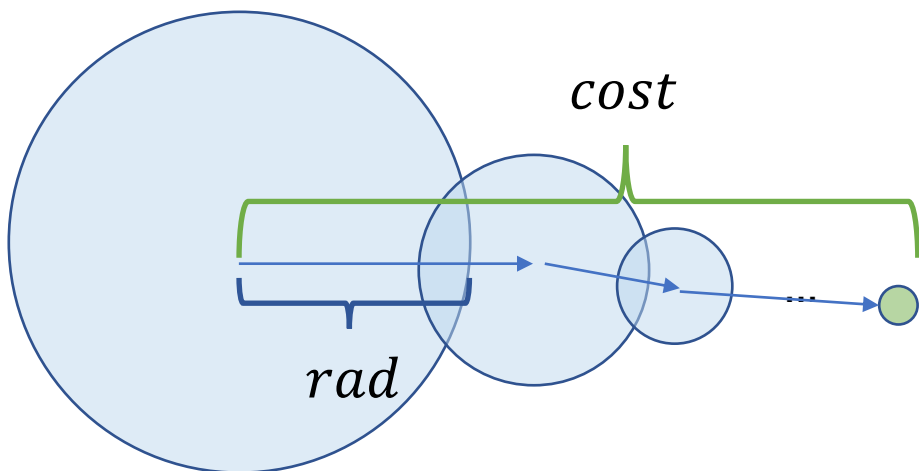
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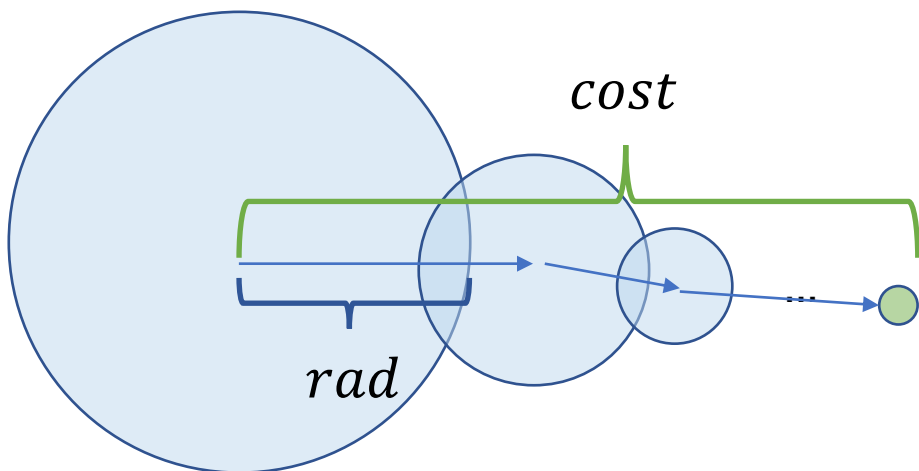
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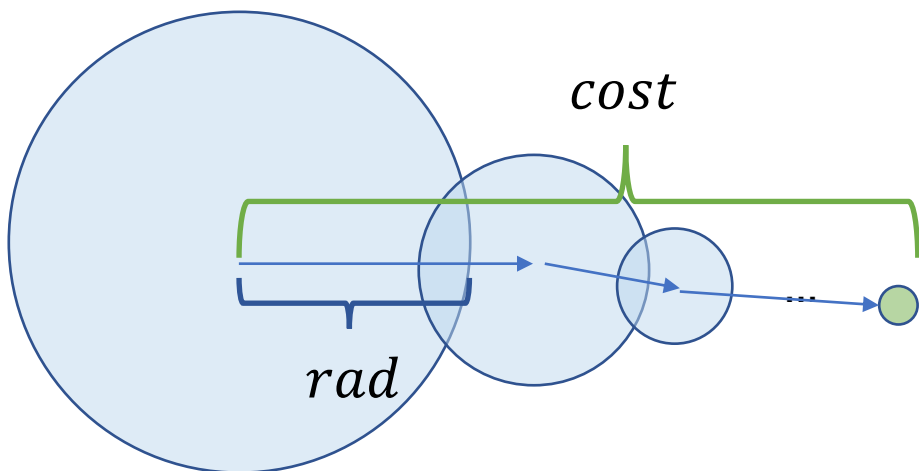
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 $\Rightarrow$  ***cost =  $O(1)$  rad***

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**Assume:** Client connection cost = *rad*

# Improving KLS: Our Techniques

- **Our Improvement:**

- Desired Structure = **two sets of** disjoint balls
- Modify = if **3 balls** intersect  $\Rightarrow$  delete **largest** radius one

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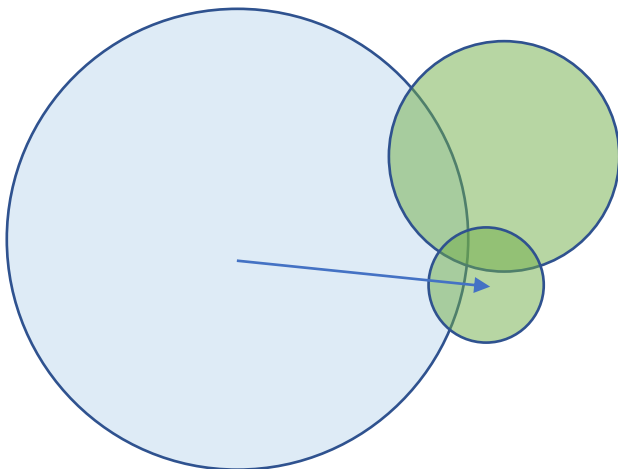
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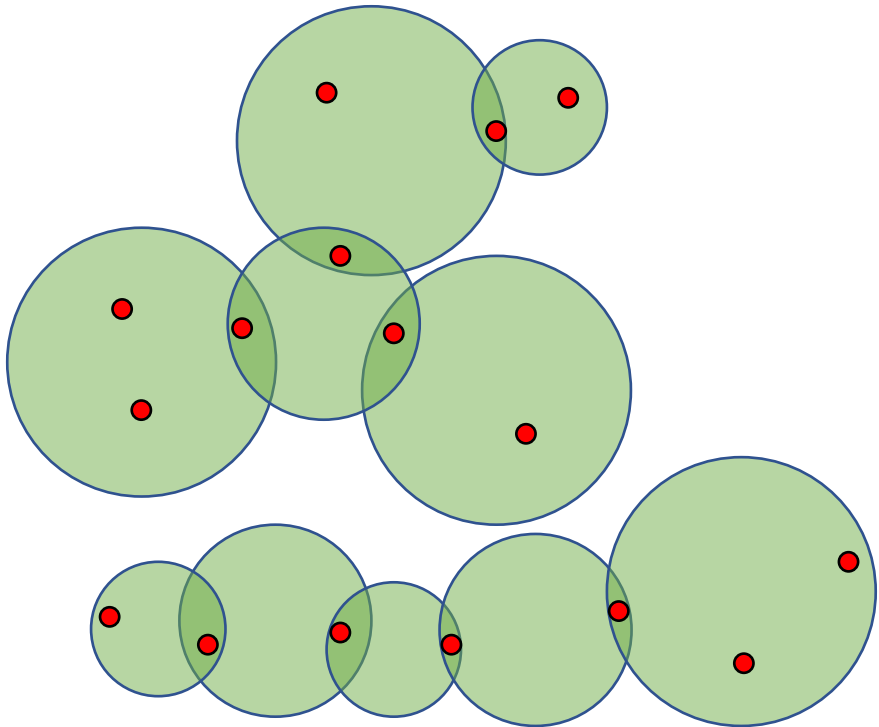
Extra dist. **quarters** at each step

# Technical Challenges

- Extra dist. halves  $\Rightarrow$  Extra dist. quarters (Improved approx. ratio)

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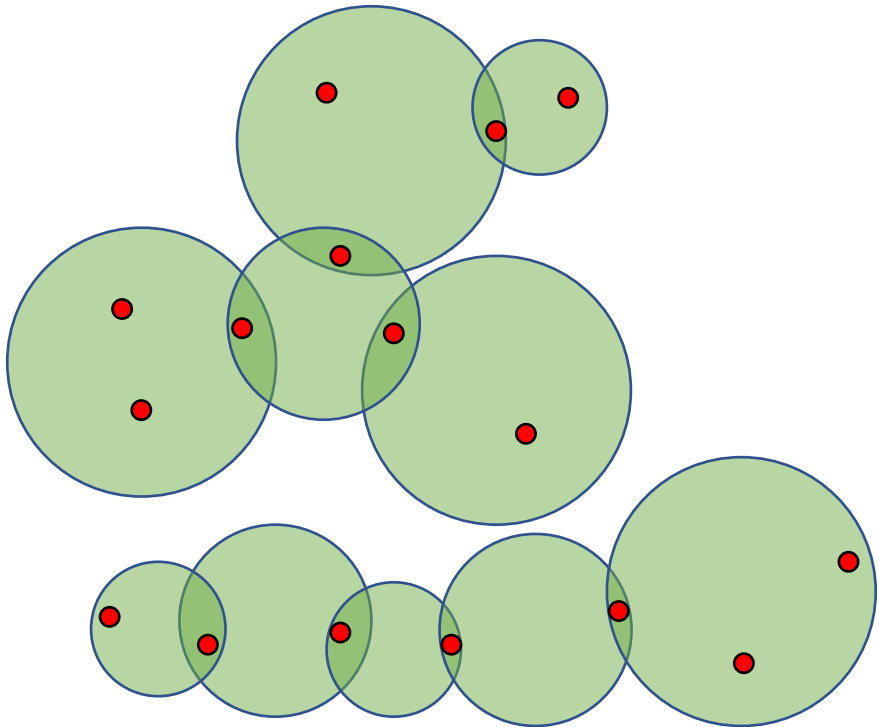
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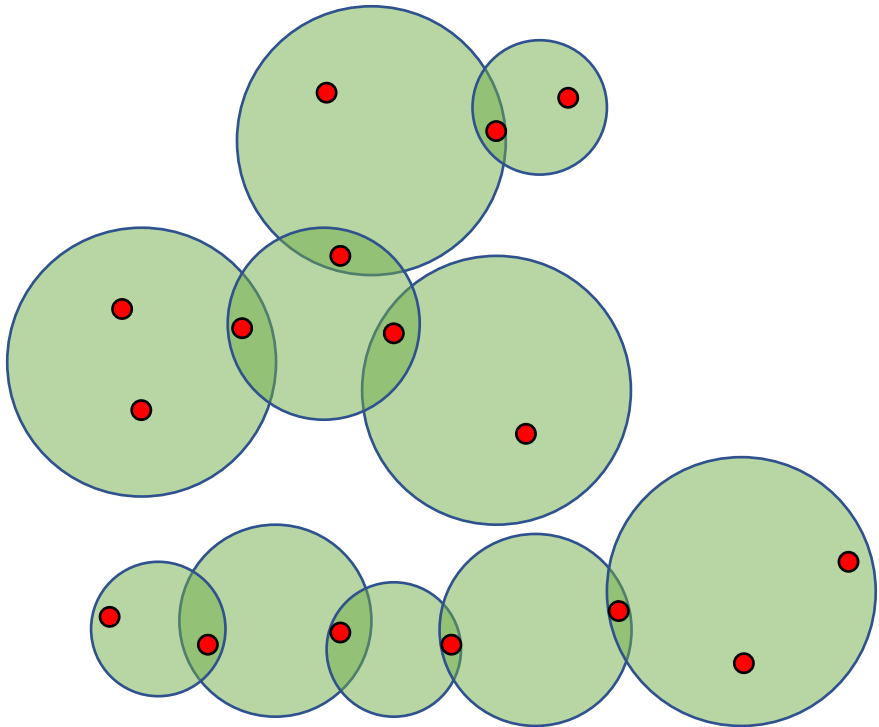
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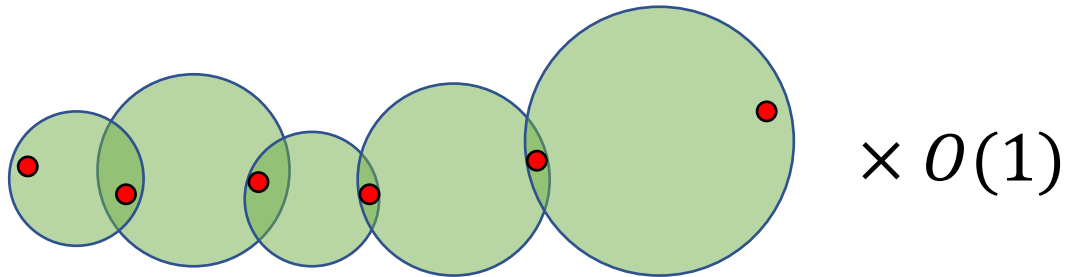


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**Main Technique:** Show that extreme points are **highly-structured**; use structure to **further modify** balls

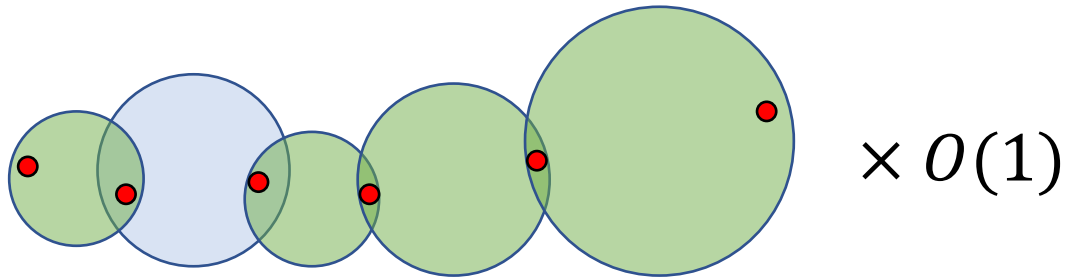
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Use chains to modify balls

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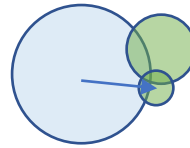
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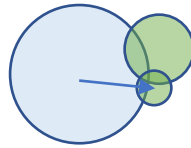
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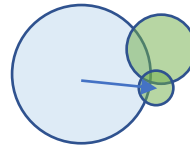
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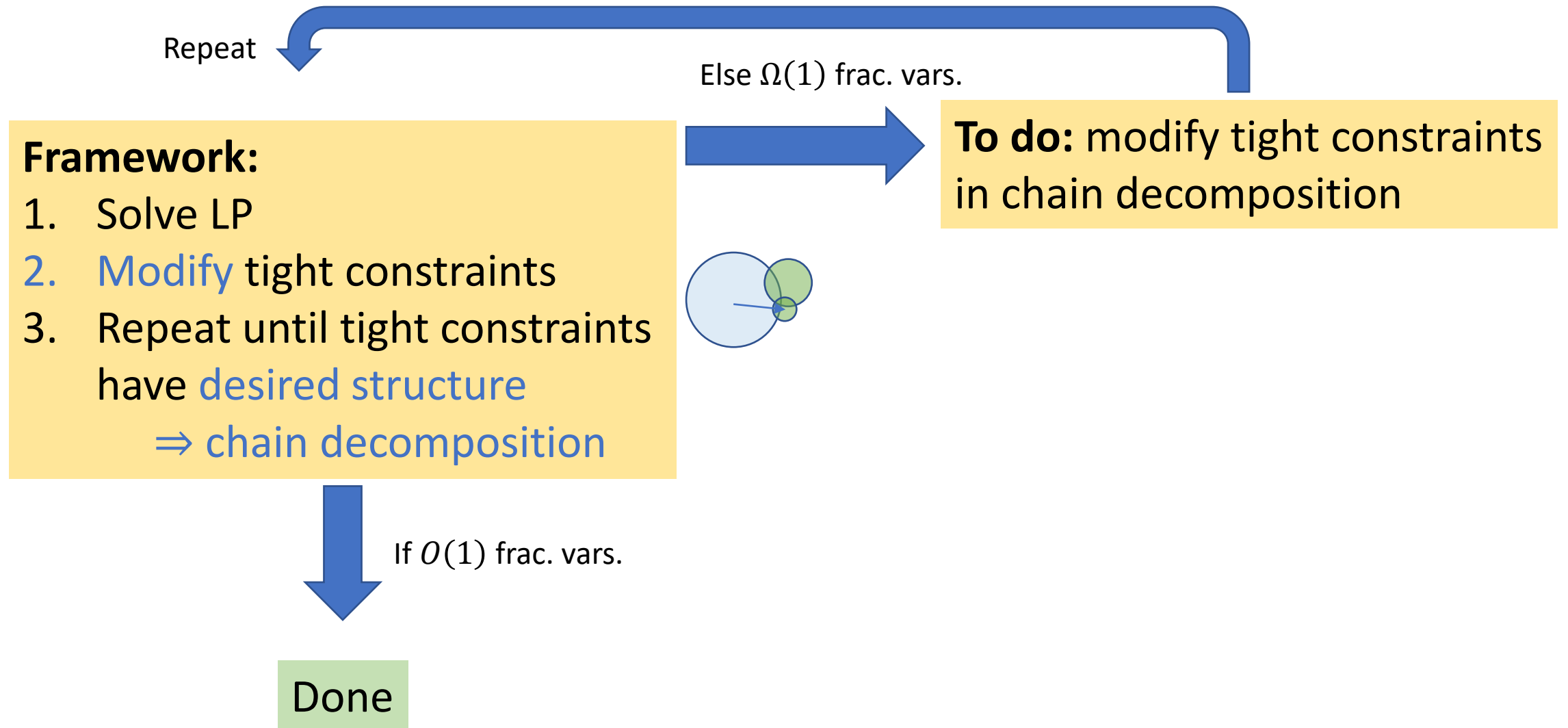
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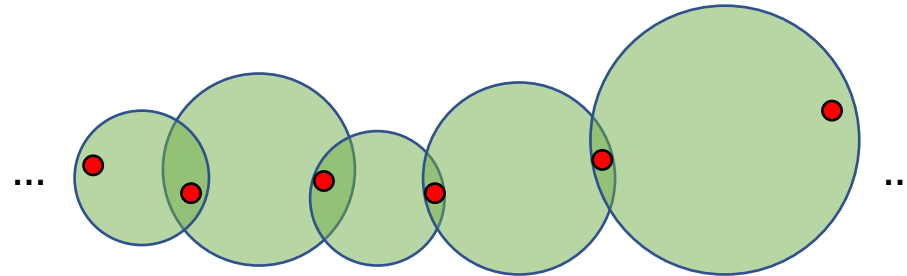
Done

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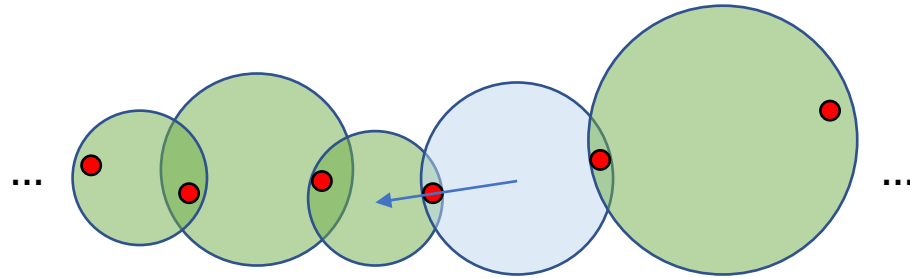
# Using Chain Decompositions

- $\Omega(1)$  frac. vars.  $\Rightarrow$  some chain is **long**



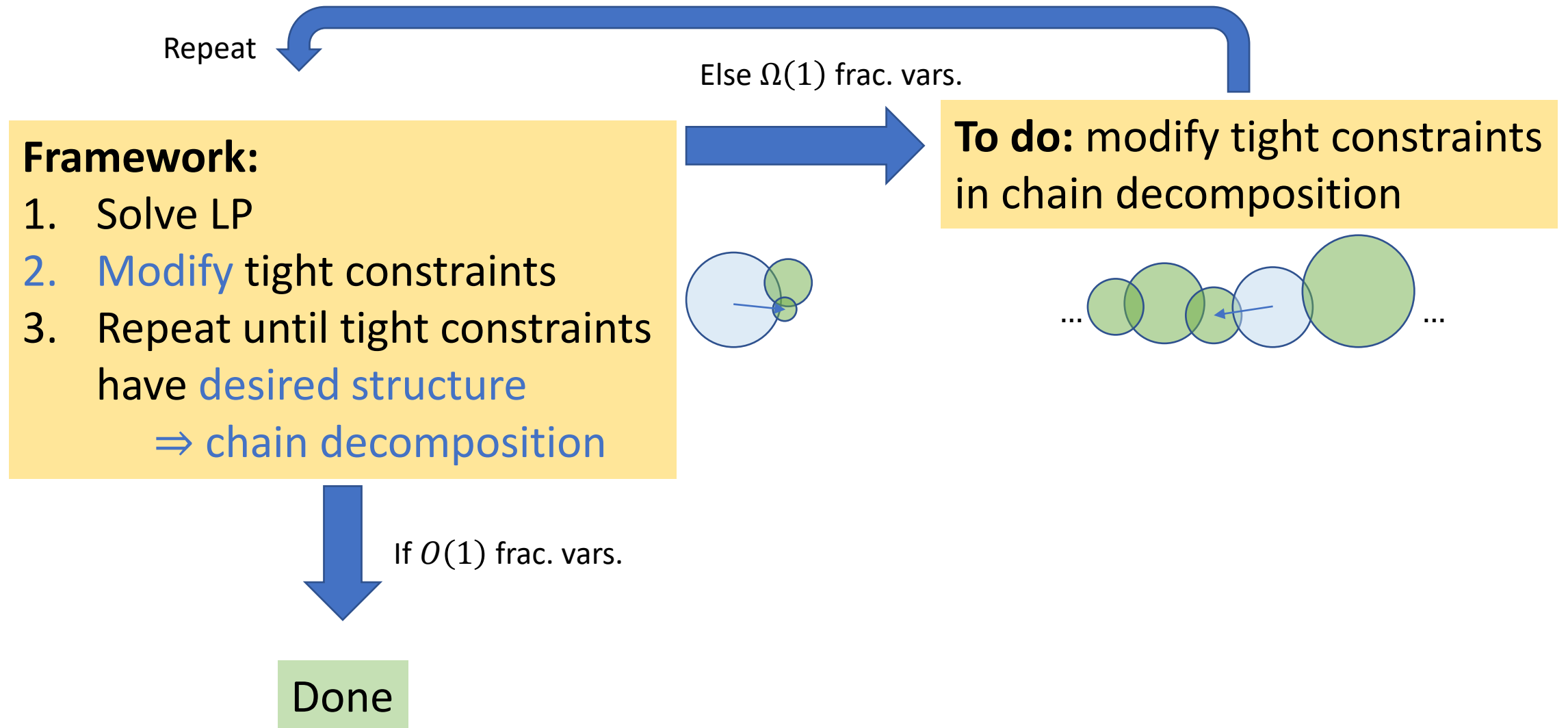
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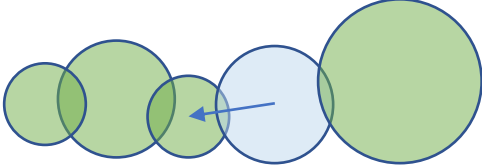
- $\Rightarrow$  delete ball in **middle** with **larger radius**

# Updated Framework



# Final Approx.

- Quarter-steps: A diagram showing a large light blue circle on the left and a smaller light green circle on the right. A blue arrow points from the center of the blue circle towards the center of the green circle.

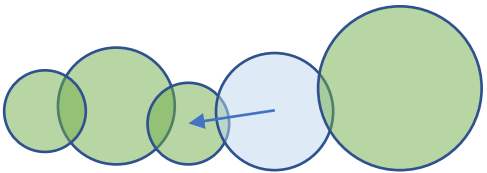
Half-steps: ...  ... A sequence of five circles: a small light green circle, a medium light green circle, a small light green circle, a medium light blue circle, and a large light green circle. Blue arrows point from the center of the second green circle to the center of the third green circle, and from the center of the fourth green circle to the center of the blue circle. Ellipses are placed at both ends of the sequence.



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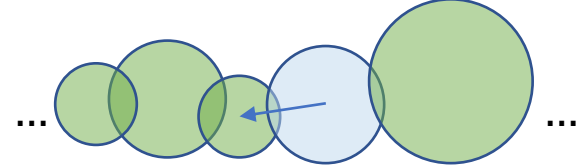
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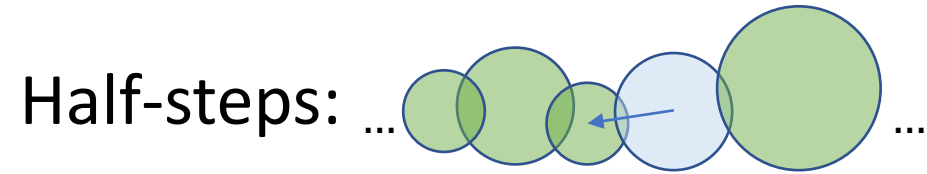
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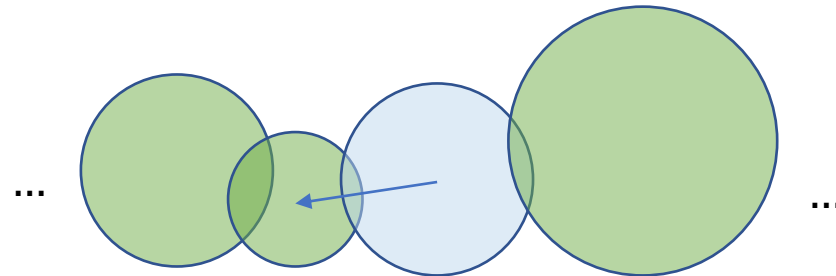
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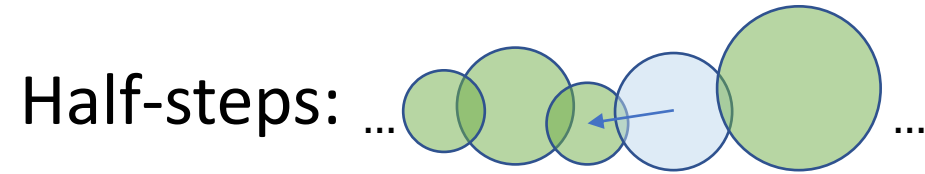


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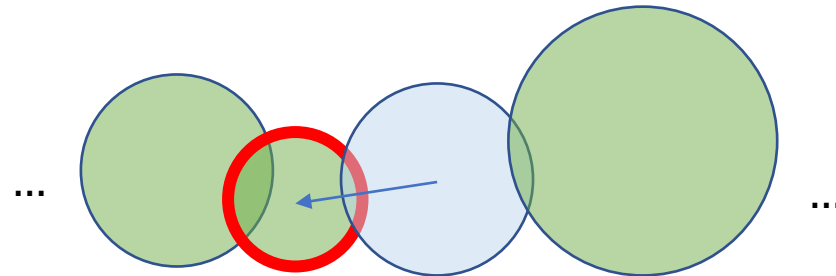


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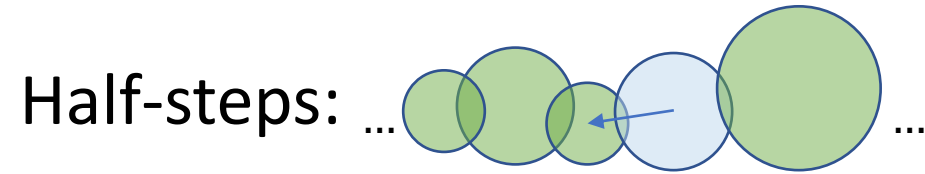


**Our Alg.:** every half-step followed by quarter-step

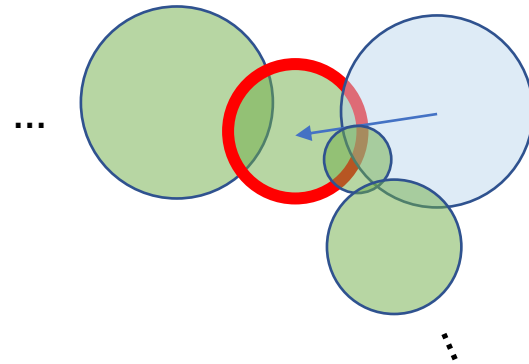


# Final Approx.

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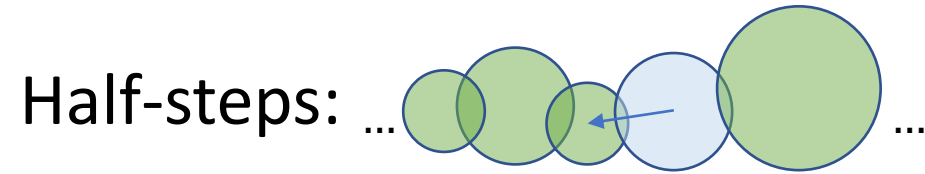


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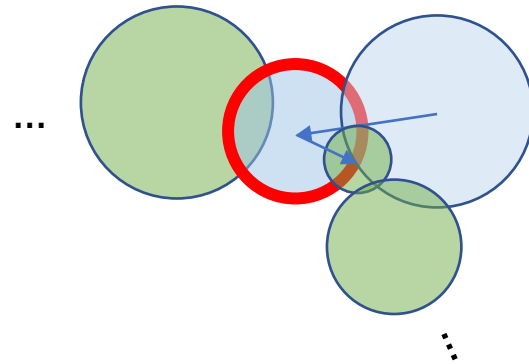


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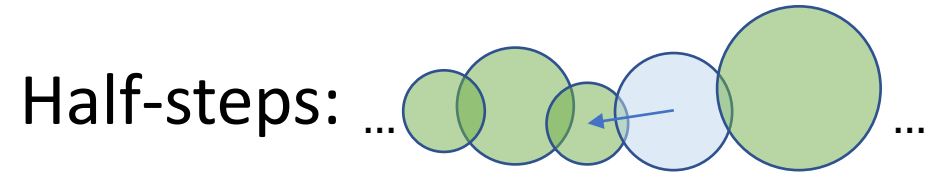


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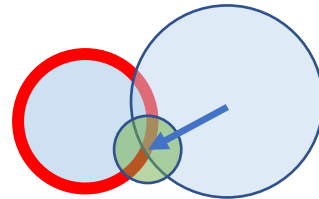


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## Open Questions:

- Can we allow even richer sets of tight constraints?
- Can we approximate  $k$ -Median with other side constraints?  $O(1)$ -many knapsack/coverage constraints?